



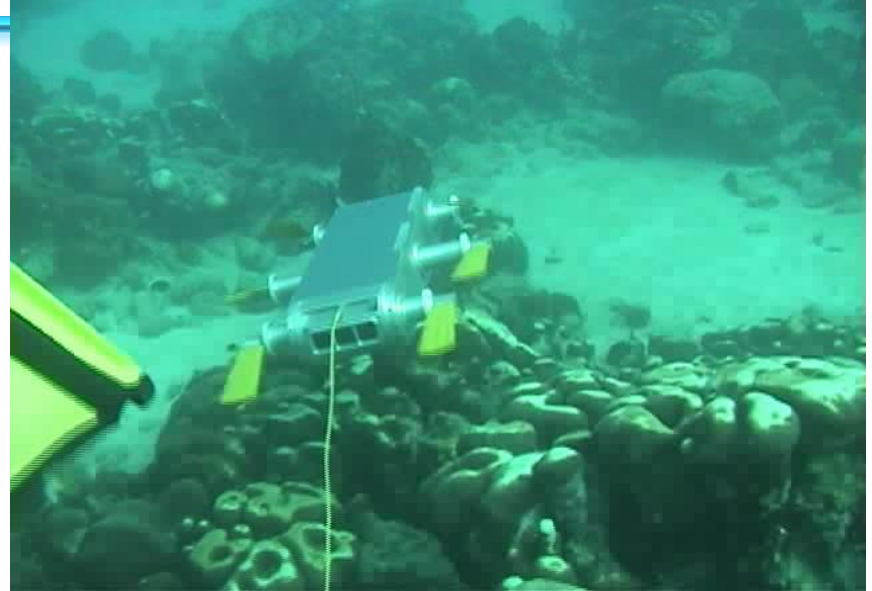
# CS-417 INTRODUCTION TO ROBOTICS AND INTELLIGENT SYSTEMS

## Introduction

# Why Robotics



Mars Exploration Rover animation



Underwater exploration, Barbados



Roomba vacuuming robot in action.

More than 5M sold!



Planetary exploration experiment at CSA



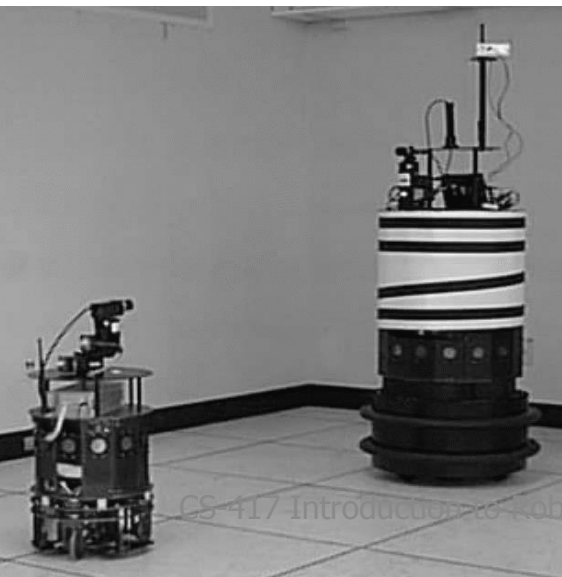
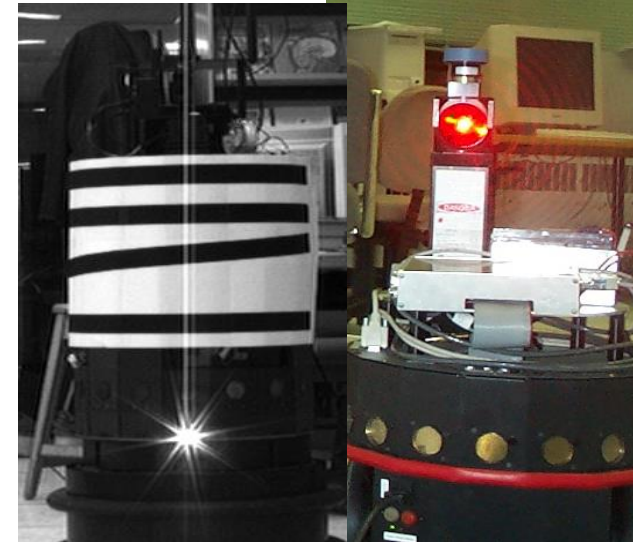
# Why Robotics?

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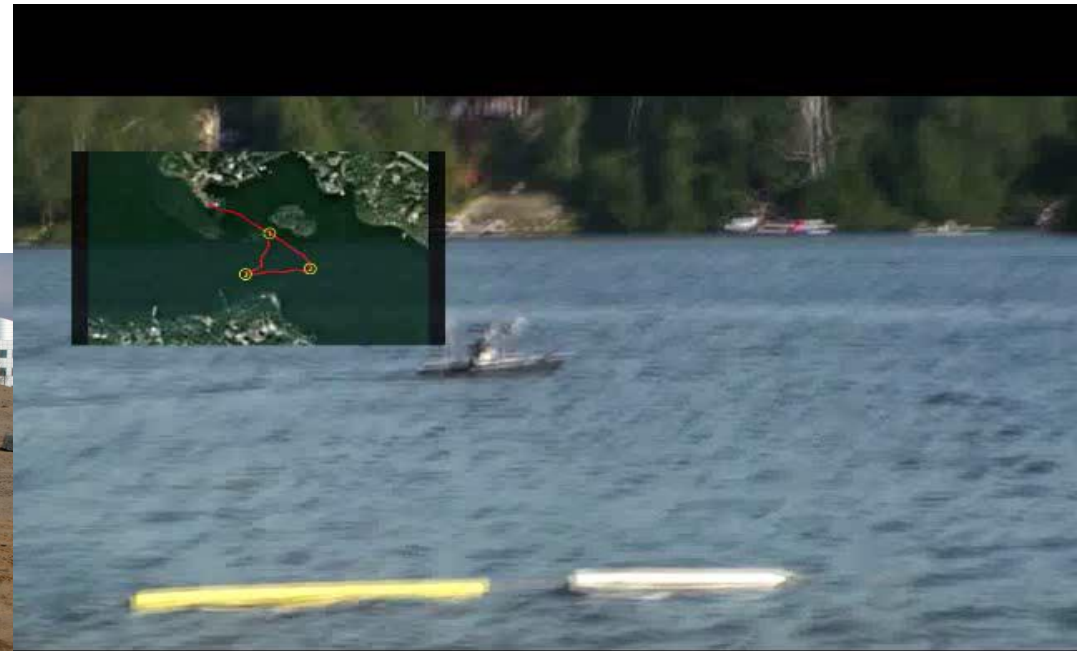
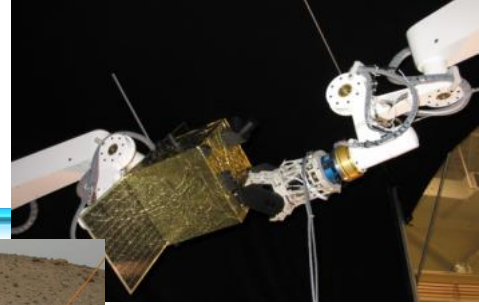
- Manufacturing
- Labor shortage (agriculture, mining)
- Point where computers fast/cheap
- Automation of cars → more cars on highways
- To reach areas where no human can go



# Past Projects



# Past/Current Projects



# Current work in U/W Robotics

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# Three Main Challenges in Robotics

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1. Where am I? (Localization)
2. What the world looks like? (Mapping)
  - Together 1 and 2 form the problem of *Simultaneous Localization and Mapping* (SLAM)
3. How do I go from **A** to **B**? (Path Planning)
  - More general: Which action should I pick next?
  - What should I do next? (Planning)



# Syllabus

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**Week 1:** Syllabus presentation, Round Table, Introduction, History of Robotics.

**Week 2:** Actuators. Locomotion. Manipulators.

**Week 3:** ROS, Control

**Week 4:** Sensor (Tactile, Range Finders, GPS, IMU, Position Encoders).

**Week 5:** Mapping: Metric Maps, Topological Maps, hybrids

**Week 6:** Sensor (Vision).

**Week 7:** Visibility Graphs, Bug Algorithm, Potential Fields.

**Week 8:** Generalized Voronoi Graphs, Atlas.

**Week 9: Mid-Term.** Semantic hierarchy of spatial representations. Configuration Space, PRMs

**Week 8:** Architectures. HRI

**Week 9:** Coverage, Multi-Robot Coverage

**Week 10:** State Estimation, Dead reckoning, Landmarks, Bayesian Filtering

**Week 11:** Particle Filters, Kalman Filters, SLAM

**Week 12:** SLAM, BoeBots tutorial

**Week 13:** Planetary Exploration, On-Orbit Servicing of Satellites, Underwater Robots

**Week 14:** In class demo, Review of Material

**Week 15: Final**





# Evaluation

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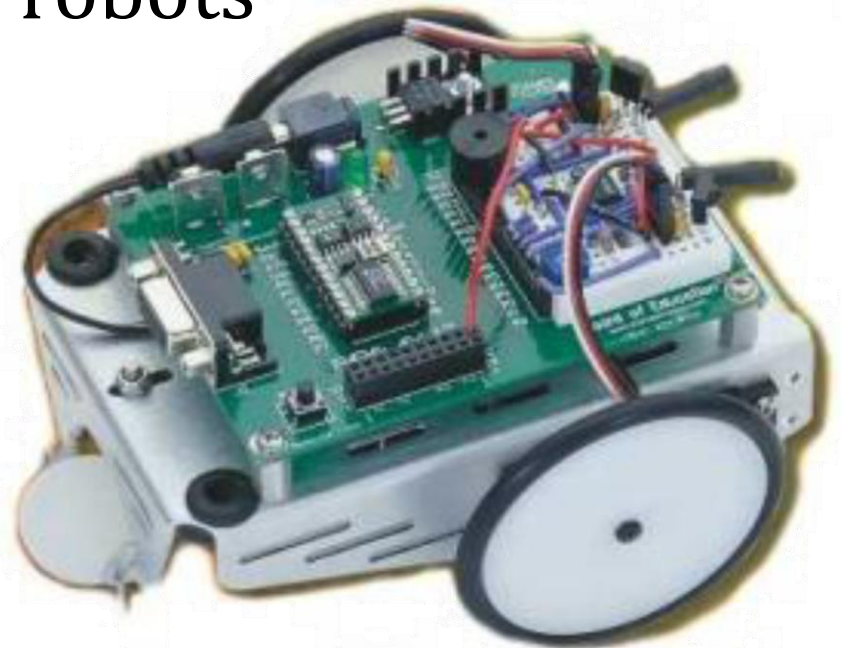
- 3 Assignments, 10% each: 30%
- Midterm Examination: 10%
- Final Examination: 35%
- Team Project 20%
- In class participation 5%



# Assignments

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- Using ROS
- Using Simulations
- Using sensor data from real robots
- Using real robots (BoeBots)



# Contacts

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- TA: Malika Meghjani



# Walter's *Tortoise* 1950's

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<http://www.youtube.com/watch?v=1LULRlmXkKo>

