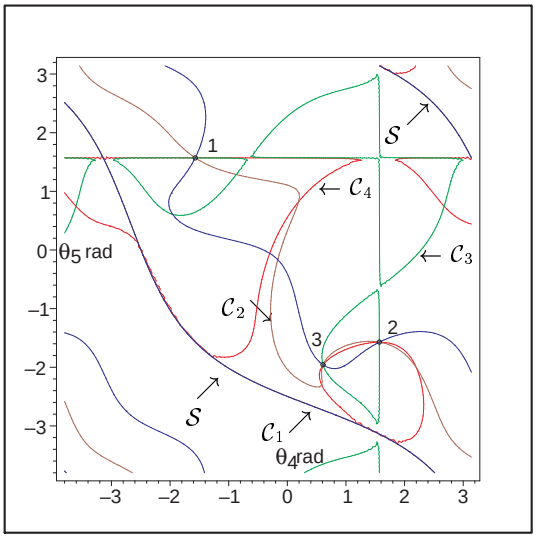

Contours $\mathcal{C}_1$, $\mathcal{C}_2$, $\mathcal{C}_3$, and $\mathcal{C}_4$ for the DIESTRO manipulator at given pose